

## MODEL ANSWER

#### WINTER-17 EXAMINATION

#### Subject Title: Electronic Instruments & Measurements

<u>Important Instructions to examiners:</u>

Subject Code:

17317

- 1) The answers should be examined by key words and not as word-to-word as given in the model answer scheme.
- 2) The model answer and the answer written by candidate may vary but the examiner may try to assess the understanding level of the candidate.
- 3) The language errors such as grammatical, spelling errors should not be given more Importance (Not applicable for subject English and Communication Skills.
- 4) While assessing figures, examiner may give credit for principal components indicated in the figure. The figures drawn by candidate and model answer may vary. The examiner may give credit for anyequivalent figure drawn.
- 5) Credits may be given step wise for numerical problems. In some cases, the assumed constant values may vary and there may be some difference in the candidate's answers and model answer.
- 6) In case of some questions credit may be given by judgement on part of examiner of relevant answer based on candidate's understanding.
- 7) For programming language papers, credit may be given to any other program based on equivalent concept.

Q. No.	Sub Q.N.	Answer	Marking Scheme
Q.1	<b>A</b> )	Attempt any six :	12-Total Marks
	<b>a</b> )	Define the term 'accuracy' and 'sensitivity' .	2M
	Ans:	Accuracy: The degree of closeness with which an instrument approaches the true value of	1M each
		the quantity being measured is known as accuracy.	
		Sensitivity: The ratio of change in output of an instrument to the change in input is known	
		as sensitivity. Sensitivity = Change in output/ Change in input.	
	b)	State the types of standards of measurement.	2M
	Ans:	International Standard	1/2M each
		Primary Standard	
		Secondary Standard	
		Working Standard	
	<b>c</b> )	List four application of CRO.	2M
	Ans:	1. It is used in laboratory for measurement of AC/DC voltage, current, frequency, phase and study nature of waveform.	<sup>1</sup> / <sub>2</sub> M each
		<ol> <li>It is used in TV receiver for creation of images.</li> </ol>	
		3. It is used in radar receiver for giving visual indication of target such as aeroplane, ship	
		etc.	
		4. It is used to test AF circuit for different distortion.	
		5. It is used to check faulty component.	



	6. It is used to check signals at radio and TV receiver.	
	7. It is used to check B-H curve of different ferromagnetic material.	
	8. It is used in medical equipment such as ECG, patient monitor.	
	9. It is used to check modulation percentage of modulated wave.	
	<b>10.</b> It is also used to check radiation pattern generated by antenna.	
<b>d</b> )	List four dynamic characteristics.	2M
Ans:	Characteristics-	
	Speed of response	<sup>1</sup> / <sub>2</sub> M each
	• Lag	
	• Fidelity	
	Dynamic Error	
e)	State two advantages of moving coil instrument.	2M
Ans:	Advantages-	1M each
	1. It has uniform scale.	
	2. Power consumption is low	
	3. It can be obtained in wide ranges.	
	4. High sensitivity & accuracy	
	5. It is unaffected by external magnetic field.	
	6. Additional damping device not required.	
	7. Hysteresis problem is not there.	
<b>f</b> )	What is the requirement of shunt in multirange ammeter?	2M
Ans:	Requirement-	1M any two
	1. The temperature coefficients of the shunt and instruments should be low and nearly identical	
	2. The resistance of shunt should not vary withj time.	
	3. It should carry the current without excessive temperature rise.	
	4. It should have a low thermal emf.	
g)	What is the role of delay line in CRO ?	2M
Ans:	The delay line is used in CRO to delay the signal for some time in the vertical sections. As	2M
	horizontal channel consists of trigger circuit and time based generator. this causes more	
	time to reach signal to horizontal plates than vertical plates. For synchronization of	
	reaching input signal at same time to both the plates in CRT.	214
h)	State the need of signal generators (any two).	2M
Ans:	Need-	1M each
	1. The generation of signals is an important activity of electronic development and	
	troubleshooting. Therefore a signal generator is a vital electronic instrument in	
	laboratory test setup which provides signals for general test purposes.	
	2. It is used to provide known test conditions for the performance evaluation of various electronic systems and for replacing missing signals in systems being analyzed for	
	electronic systems and for replacing missing signals in systems being analyzed for repair.	
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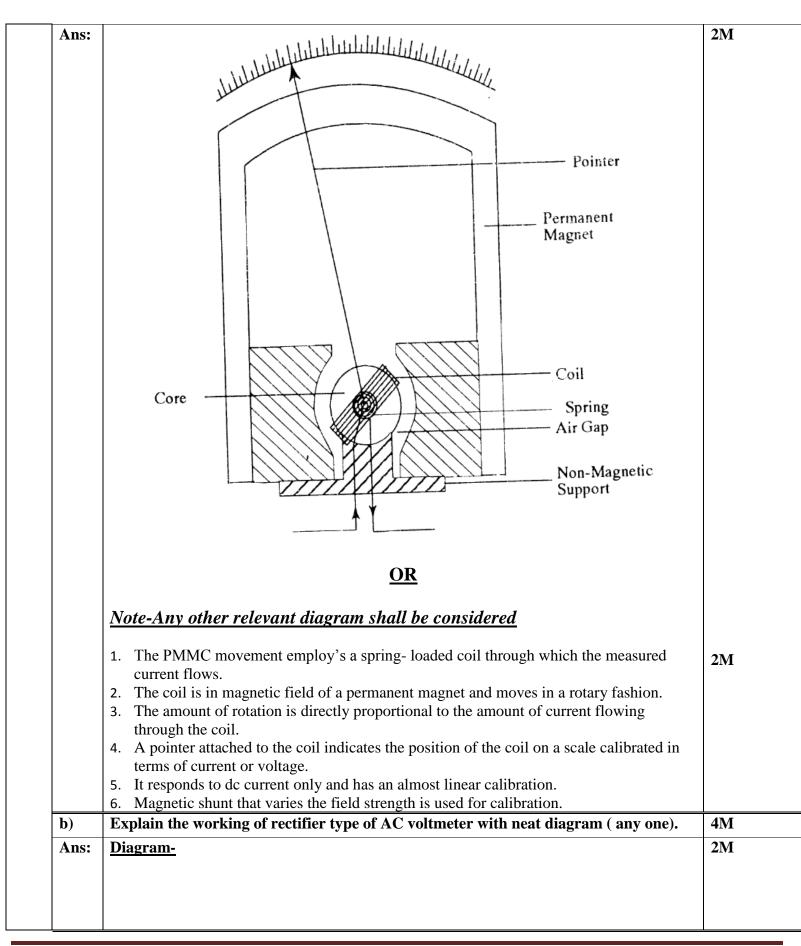


<b>B</b> )	Attempt any two:	8-Total Marks
a)	Draw the circuit diagram of DC ammeter using basic 'D' Amsoval movement and derive the expression for shunt resistance.	4M
Ans:	<u>Circuit diagram-</u>	2M
	Image: Second	2M
<b>b</b> )	Give significance of calibration.	4M
Ans:	Calibration:	4M

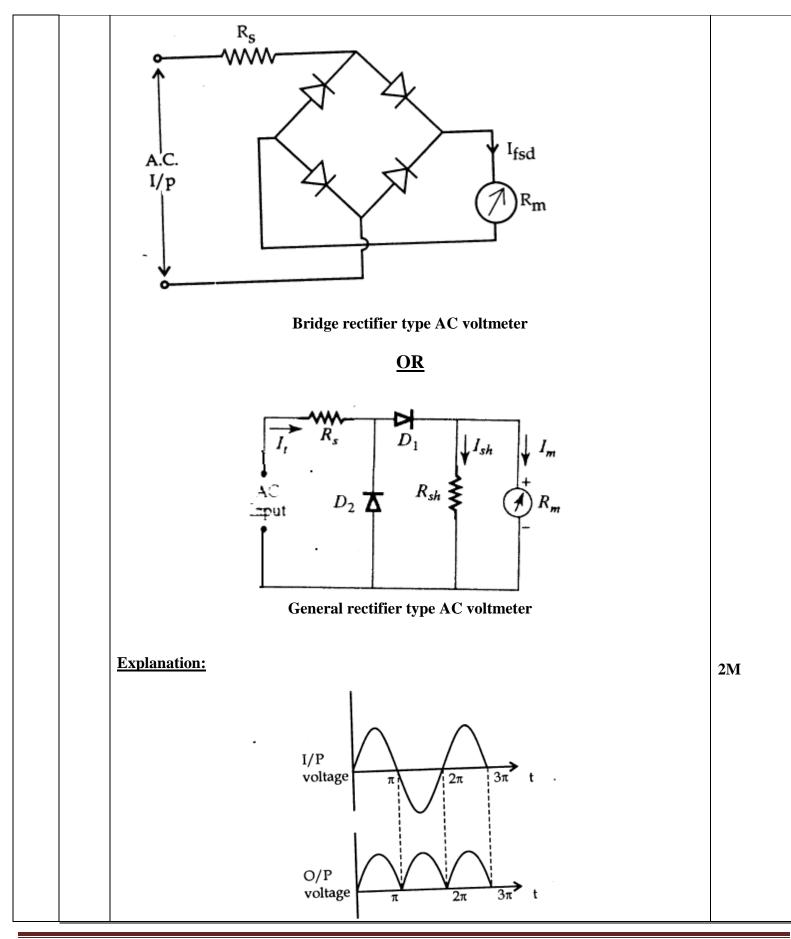


	<b>a</b> )	Describe the construction of PMMC instrument.	<b>4M</b>
Q. 2		Attempt any four :	16-Total Marks
		<ul><li>systematic and gross error are removed,</li><li>2. Dynamic error: the difference between true value of a quantity changing with time and value indicated by instrument if no static error is assumed is called as dynamic error.</li></ul>	
		<ul> <li>observation error: these are introduced by the observer, the most common error is the parallex error introduced in reading a meter scale.</li> <li>iii. Random error: these errors are due to unknown causes, these error remain since the</li> </ul>	
		<ul> <li>Environmental error: these errors occur due to external condition to the measuring instrument, such as temperature, pressure, humidity, dust and external magnetic field.</li> <li>Observation error: these are introduced by the observer. the most common error is the</li> </ul>	
		<ul> <li>Instrumental error: the errors which arise due to inherent shortcoming of instrument, misuse of instrument, loading effect of instrument are called as instrumental error.</li> <li>Environmental error: these errors occur due to external condition to the measuring</li> </ul>	
		ii. <b>Systematic errors</b> : these errors occur due to shortcoming of the instrument such as defective or worn part or aging or effect of environment on the instrument.	
		handling instrument incorrect setting or adjustment and improper use of instrument are known as gross errors.	
		i. Gross errors: the errors which occur due to human mistakes while taking reading,	explanation
		The error which occurs in stationary condition is called as static error. These are classified as:	3M explanation
	c) Ans:	List different types of errors and its source of generation/occurrence. 1. Static error :	1M- List
		4. Calibration increases productivity, optimizes resources and assures consistency	4M
		3. To establish the reliability of the instrument i.e. it can be trusted.	
		2. To determine the accuracy of the instrument reading.	
		Need of calibration:1. To ensure reading from an instrument are consistent with other measurements.	











In full wave bridge rectifier the output voltage is double that of half wave rectifier. If we assume diode has zero forward resistance and infinite reverse resistance then,  $R_s = \frac{V_{dc}}{I_{fed}} - R_m$ where,  $R_s \rightarrow$  series resistance.  $V_{dc} \rightarrow d.c.$  output voltage.  $I_{fsd} \rightarrow$  full scale deflection current.  $R_m \rightarrow$  Internal resistance of meter. If sinusoidal voltage is applied at input, then the output voltage is given by,  $V_{dc} = \frac{2}{2\pi} \int_{0}^{\pi} V_{m} \sin \omega t .d\omega t$  $=\frac{1}{\pi}(-V_{\rm m})\left[\cos\omega t\right]_0^{\pi}$  $=\frac{-V_{m}}{-1}[-1-1]$  $V_{dc} = \frac{2V_m}{\pi}$ ----- (1) we know.  $V_{\rm rms} = \frac{V_{\rm m}}{\sqrt{2}}$  $\therefore V_{\rm m} = \sqrt{2} V_{\rm rms}$ Put this value in equation (1)  $\therefore V_{dc} = \frac{2\sqrt{2} V_{rms}}{\pi}$  $\therefore V_{dc} = 0.903 V_{rms}$ The above equation shows that such type of voltmeter shows 90.3% efficiency that of d.c. voltmeter.

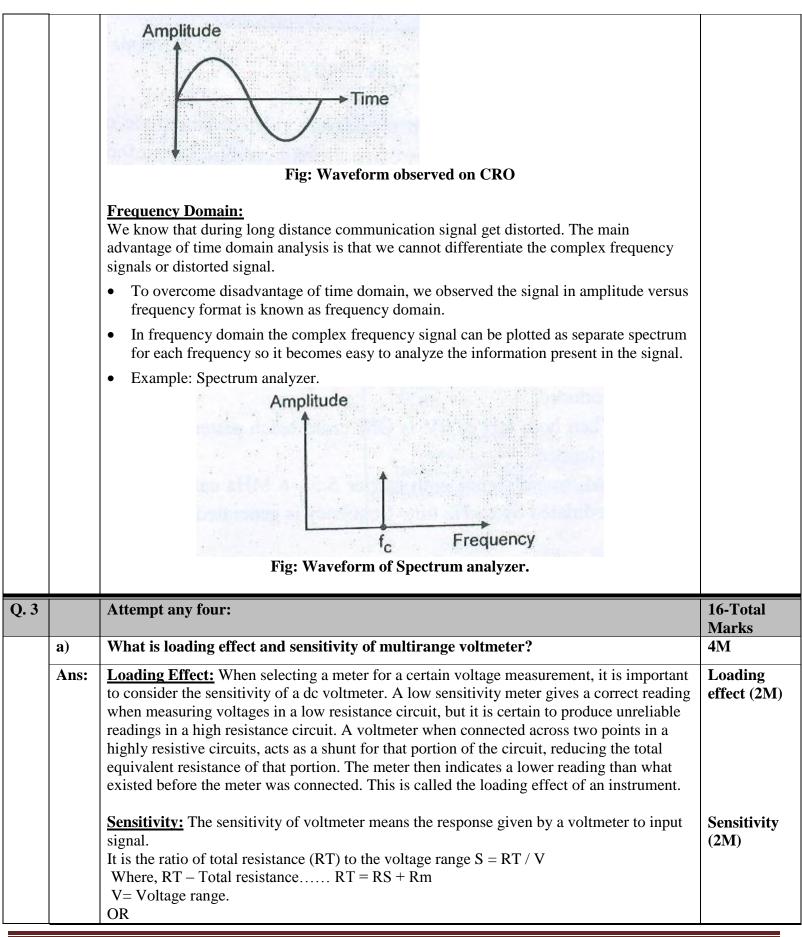


	OR	
	<u>Note-Any other relevant diagram shall be considered (half wave can be</u> <u>considered)</u>	
<b>c</b> )	State the reason for voltmeter never connected in series with source of emf.	4M
Ans:	The voltmetre is used for measuring the electrical potential difference between two points of a line ,where as the potential difference measured between two points of same wire/line is zero. In short, the internal resistance of voltmetre is generally high, so you cannot connect it in series.	4M
d)	Explain the block diagram of DFM (Digital Frequency Meter).	4M
Ans:	Block diagram –	2M
	Unknown Amplifier Schmitt Start-stop Counter and signal Interest Schmitt Start-stop Display	
	OR	
	Input Signal Ampli- Schmitt Schmitt Schmitt Gate	
	Trigger F/F Time Base Selector 1 sec 100 ms	
	1 MHz Crystal Oscillator Fig. 6.7 Block diagram of a digital frequency meter	
	Explanation: Digital frequency meter:	2M



	of unknow	n signal. These pulses are directly prop	portional to the frequency to be measured.		
	Amplifier:				
	<ul> <li>The signal whose frequency is to be measured is first amplified. The output of amplifier is applied to the Schmitt trigger.</li> </ul>				
	<ul> <li>Schmitt trigger:</li> <li>The Schmitt trigger converts the signal into square wave having fast rise and fall times.</li> <li>The square wave is then differentiated and clipped. Each pulse is proportional to each cycle of unknown signal.</li> </ul>				
	-	<b>ate:</b> t from Schmitt trigger is applied to st the switch.	art and stop gate. These pulses are		
	This switch		inite time interval. The main gate switch		
	• When the		to pass through it. A counter will now		
	• When the	gate is closed, input pulses are not al ill now stop counting.	lowed to pass through the gate. The		
	<ul> <li><u>Counter and display:</u></li> <li>The number of pulses during the period gate is open are counted by the counter.</li> <li>If this interval between start and stop condition is known, the frequency of unknown</li> </ul>				
		_	is known, the frequency of unknown		
	signal is m F= N/t	_	is known, the frequency of unknown		
	signal is m	neasured.	is known, the frequency of unknown		
	signal is m F= N/t Where, F= Unknown t N= Number of	heasured. frequency f counts displayed by the counter.			
	signal is m F= N/t Where, F= Unknown t N= Number of t= Time interv	heasured. frequency f counts displayed by the counter. val between start and stop condition of			
2)	signal is m F= N/t Where, F= Unknown t N= Number of t= Time interv	heasured. frequency f counts displayed by the counter.		4M	
	signal is m F= N/t Where, F= Unknown t N= Number of t= Time interv Compare DS	frequency f counts displayed by the counter. val between start and stop condition of <b>O with CRO (any four points).</b>	of the gate.	1M each	
-	signal is m F= N/t Where, F= Unknown t N= Number of t= Time interv	frequency f counts displayed by the counter. val between start and stop condition of O with CRO (any four points). CRO	of the gate.	1M each any four	
	signal is m F= N/t Where, F= Unknown t N= Number of t t= Time interv <b>Compare DS</b> <b>SR.NO</b> 1	frequency f counts displayed by the counter. val between start and stop condition of <b>O with CRO (any four points).</b> CRO It is analog oscilloscope	of the gate.          DSO         It is digital oscilloscope	1M each	
	signal is m F= N/t Where, F= Unknown t N= Number of t t= Time intervent Compare DSC 1 2	frequency f counts displayed by the counter. val between start and stop condition of <b>O with CRO (any four points).</b> CRO It is analog oscilloscope Less accurate	of the gate.           DSO           It is digital oscilloscope           More accurate	1M each any four	
	signal is m F= N/t Where, F= Unknown t N= Number of t t= Time intervent Compare DSC 1 2 3	frequency f counts displayed by the counter. val between start and stop condition of <b>O with CRO (any four points).</b> CRO It is analog oscilloscope Less accurate No memory	of the gate.           DSO           It is digital oscilloscope           More accurate           Memory present	1M each any four	
-	signal is m F= N/t Where, F= Unknown t N= Number of t t= Time intervent Compare DSC 1 2	frequency f counts displayed by the counter. val between start and stop condition of <b>O with CRO (any four points).</b> CRO It is analog oscilloscope Less accurate	of the gate.           DSO           It is digital oscilloscope           More accurate	1M each any four	
-	signal is m F= N/t Where, F= Unknown t N= Number of t t= Time interv Compare DS SR.NO 1 2 3 4	frequency f counts displayed by the counter. val between start and stop condition of <b>O with CRO (any four points).</b> CRO It is analog oscilloscope Less accurate No memory Cost is less	of the gate. DSO It is digital oscilloscope More accurate Memory present Cost is more	1M each any four	
Ans:	signal is m F= N/t Where, F= Unknown t N= Number of t Time interververververververververververververve	frequency f counts displayed by the counter. val between start and stop condition of <b>O with CRO (any four points).</b> CRO It is analog oscilloscope Less accurate No memory Cost is less	of the gate. DSO It is digital oscilloscope More accurate Memory present Cost is more Can store signal	1M each any four	
Ans: f)	signal is m F= N/t Where, F= Unknown the N= Number of the term Compare DSC SR.NO 1 2 3 4 5 Explain the compared to the term $F= Unknown the term F= Unknown the term$	frequency f counts displayed by the counter. val between start and stop condition of O with CRO (any four points). CRO It is analog oscilloscope Less accurate No memory Cost is less Cannot store signal oncept of time domain and frequer	of the gate. DSO It is digital oscilloscope More accurate Memory present Cost is more Can store signal	1M each any four points4M	
e) Ans: f) Ans:	signal is m F= N/t Where, F= Unknown for $N= Number of term interverse Compare DSO 1 2 3 4 5 Explain the comparence of the second seco$	frequency f counts displayed by the counter. val between start and stop condition of O with CRO (any four points). CRO It is analog oscilloscope Less accurate No memory Cost is less Cannot store signal oncept of time domain and frequer	of the gate. DSO It is digital oscilloscope More accurate Memory present Cost is more Can store signal	1M each any four points	
Ans: f)	signal is m F= N/t Where, F= Unknown find N= Number of the term Compare DS SR.NO 1 2 3 4 5 Explain the compared by the term In general we	frequency f counts displayed by the counter. val between start and stop condition of O with CRO (any four points). CRO It is analog oscilloscope Less accurate No memory Cost is less Cannot store signal oncept of time domain and frequer	DSO         It is digital oscilloscope         More accurate         Memory present         Cost is more         Can store signal	1M each any four points4M	

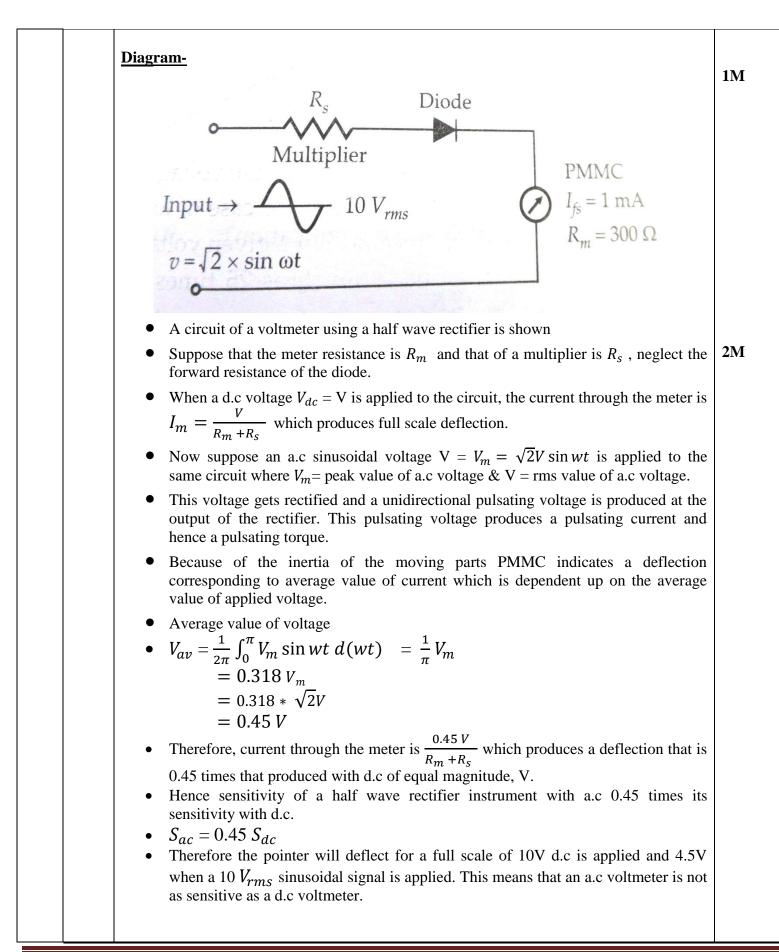






		[
	It is also defined as the reciprocal of full scale deflection current of the basic movement.	
	S = 1 / Ifsd Ifsd = full scale deflection current.	
<b>b</b> )		<b>4</b> M
b) Ans:	<ul> <li>How does electron beam generate horizontal refline on CRT screen?</li> <li>The Electron Gun Assembly produces a sharply focused beam of electron which is</li> </ul>	41 <b>VI</b> 1/2 M for
A115.		each point
	accelerated to a high velocity.	cach point
	• The electrons are accelerated by high positive potential which is applied to the pre-	
	accelerating and accelerating anodes.	
	• The electron beam is focused by the focusing anode.	
	• This focused beam of electron strikes the fluorescent screen with sufficient energy to	
	cause a luminous spot on the screen.	
	• After leaving the electron gun, the electron beam passes through two pairs of	
	'electrostatic deflection plates'. The voltages applied to these plates deflect the beam.	
	• Voltages applied to horizontal deflecting plates move the beam horizontally from one	
	side to another.	
	• Due to the horizontal movement the beam is positioned horizontally on the screen and	
	a horizontal trace on CRO screen is obtained	
c)	Write the steps (and procedure) for measurement of frequency and phase of signal by	4M
	CRO.	
Ans:	Phase :	Phase-2M
	The phase measurement can be done by using Lissajous figures.	
	The CRO is set to operate in the X-Y mode, then the display obtained on the screen of a	
	CRO is called Lissajous pattern, when two sine waves of the same frequency are applied to the CRO.	
	(One vertical and one horizontal deflection plates).	
	Depending on the phase shift between the two signals, the shape of the Lissajous pattern	
	will go on changing.	
	The phase shift is given by,	
	$\Theta = \sin -1 (A/B)$	
	Frequency :	-
	• The period and frequency of periodic signals are easily measured.	Frequency- 2M
	• The period is the time between two identical points of successive cycle of the waveform.	2111
	Period= no of divisions $\times$ position of time/div knob.	
	• The frequency is inversely proportional to the period.	
	Frequency= 1/Period	
d)	How does Halfwave rectifier typeAC analog voltmeter use to measure unknown voltage.	<b>4M</b>
A		
Ans:		

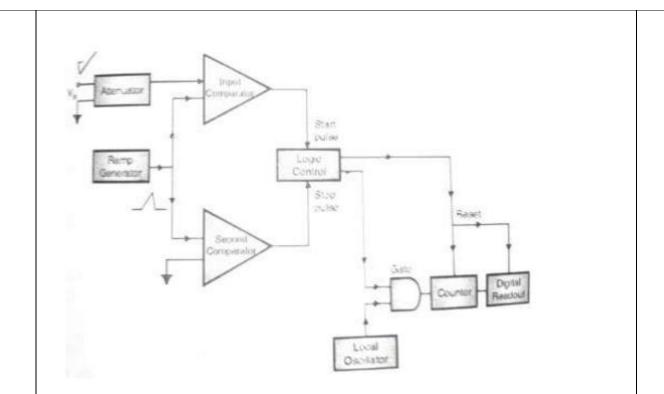






	$V_{m}$ $V = V_{rms} = V_{m}/\sqrt{2}$ $0$ $\pi$ $2\pi$ $3\pi$ of Input $V_{m}$	1M
e)	$\frac{\pi}{2\pi} \frac{2\pi}{3\pi} \frac{3\pi}{0}$ Calculate the value of multiplier, i fbasic movement having (l fsd) full scale deflection current of lOrnA and Internal resistance Rm of 50 n is used to measure 400 volts.	4M
Ans:	Given data: Ifsd=10mA $Rm=50\Omega$ V=400volts.	
	$Rs = \frac{V}{Im} - Rm$	1M
	$=\frac{400}{10\mathrm{mA}}-50\Omega$	1M
	$\begin{array}{rcl} Rs = & 40000-50 \\ Rs = & 39950 \Omega \end{array}$	1M
	$Rs= 39.95k\Omega$	11/
<b>P</b> )	Describe the block diagram of Ramp type of voltmeter.	1M 4M
1)	Block diagram-	2M
· ·	Diver ungrun	
<u>f)</u> Ans:		





# Working:

Unknown voltage to be measured is applied to the input side.

- Initially the logic circuit sends the reset signal to the counter and digital readout.
- Before the starting of measurement the counter and digital readout are resetted.

• The ramp generator, generates the ramp wave. This ramp may be positive going or negative going. Consider a positive going ramp. This ramp signal is applied to the both of the comparators.

• Here each comparator is design in such a way that when both the input signals of a comparators are equal then the comparator changes its states. That means when both input signals are equal then the output voltage swing of a comparator takes place.

- In this system, one comparator is used to open the gate while other comparator is used to close the gate.
- In this case we have considered a positive going ramp pulse.
- The reference voltage for the second comparator is the ground level.
- When the ramp signal crosses the zero voltage then both inputs of seconds comparators becoms equal.
- So the output stage of this comparator changes. This signal is sent to the logic control.
- The logic control circuit gives the signal to the logic gate. This causes the opening of gate.
- Once the gate is opened; the counter starts counting the number of pulses. These number of pulses are provided by the local oscillator.
- The number of pulses generated by the local oscillator in a particular time interval depends on the frequency of local oscillator.
- The ramp signal is applied to both comparators. One input terminal of first comparator is connected to the input unknown voltage.

• When the ramp voltage becomes equal to input unknown voltage; then both input signals of first comparators are equal. So the output stage of this comparator are changes.

**2M** 



	<ul> <li>will stop the</li> <li>During the</li> <li>pulses will be</li> </ul>	ate is closed, the numbe counting operation.	opening and closing the ga	ng to counter. So the counte	r
<b>A</b> )	Attempt any	four:			16-Total Morks
a)	Compare an	alog instruments with	digital instruments.		Marks 4M
Ans:		0			each 1M
	Sr. No.	Parameter	Analog instrument	Digital instrument	
	1	Principle	The instrument that displays analog signals is called as an analog instrument	The instrument that displays digital signals is called as an digital instrument	
	2	Accuracy	Low	High	
	3	Resolution	Low	High	
	4	Power required	Require more power	Require less power	
	5	Cost	Cheap	costly	
	6	Portability	Portable	Less	
	7	Observational error	Considerable Observational error	Free from Observational error	
	8	examples	PMMC instrument, analog ammeter, analog voltmeter.	DMM, DVM	
b)	ammeter.	er with internal resista e value of Shunt resist	nce of 100 n is to be conv	verted to 0 - 150 rnA	<b>4</b> M
	Culculate th		-		
Ans:	Given data: Im=2mA Rm=100Ω I=1-150mA				1M
Ans:	Given data: Im=2mA Rm=100Ω I=1-150mA				1M 1M
Ans:	Given data: Im=2mA Rm=100 $\Omega$ I=1-150mA Rsh = $\frac{ImH}{I-I}$ = $\frac{2mA}{150m}$	<u>Rm</u> Im <u>A×100Ω</u> nA−2mA			
Ans:	Given data: Im=2mA Rm=100Ω I=1-150mA Rsh = $\frac{ImH}{I-I}$ $= \frac{2mA}{150m}$	<u>Rm</u> Im <u>A×100Ω</u> nA–2mA ×100Ω 8mA			1M
Ans:	Given data: Im=2mA Rm=100Ω I=1-150mA Rsh = $\frac{ImH}{I-I}$ $= \frac{2mA}{150m}$ $= \frac{2mA}{148}$ Rsh=1.3	<u>Rm</u> Im <u>A×100Ω</u> nA–2mA ×100Ω 8mA 8 <b>5Ω</b>	idvantages of PMMC me	Jtor	1M 1M



3. It can be obtained in wide ranges. 4. High sensitivity & accuracy       3. It is unaffected by verternal magnetic field.       6. Additional damping device not required.       2M         2. St is unaffected by verternal magnetic field.       6. Additional damping device not required.       2M       2M         3. It is unaffected by external magnetic field.       6. Additional damping device not required.       2M       2M         1. It is suitable for dc. measurement only.       2. Comparatively high cost than moving iron type instrument.       3. Ageing of permanent magnet & spring introduce errors       4. Priction due to jewel- pivot suspension.       4M         and fig. (b).       Image: Calculate the vertical input frequency if horizontal frequency is 1500 Hz for fig. (a) and fig. (b).       4M       4M         Ans:       Fig a.       X-2, Y - 2       1M         Fig b.       X-3, Y = 2       1M       1M         Fig b.       X-3, Y = 2       1M         Therefore, fy= X/Y x fx = 3/2 x1500Hz       1M       1M         e)       Explain the block diagram of function generator.       4M         Max:       Block diagram:       2M         e)       Explain the block diagram of function generator.       4M         Mix:       Block diagram:       2M         Fig: Function Generator.       4M         Mix: <td< th=""><th></th><th></th></td<>		
6. Additional damping device nor required.       2M         Disadvantages of PMMC meter: (Any two)       1. It is suitable for dc. measurement only.       2M         1. It is suitable for dc. measurement only.       3. Ageing of permanent magnet & spring introduce errors       4. Friction due to jewel- pivot suspension.       4M         and fig. (b).       Image: the vertical input frequency if horizontal frequency is 1500 Hz for fig. (a)       4M         Ans:       Fig. a.       Fig. a.       Image: the vertical input frequency if horizontal frequency is 1500 Hz for fig. (a)         Ans:       Fig. a.       Image: the vertical input frequency if horizontal frequency is 1500 Hz for fig. (a)       4M         Ans:       Fig. a.       Image: the vertical input frequency if horizontal frequency is 1500 Hz for fig. (a)       4M         Ans:       Fig. a.       Image: the vertical input frequency if horizontal frequency is 1500 Hz for fig. (a)       4M         Ans:       Fig. a.       Image: the vertical input frequency is 1500 Hz for fig. (a)       4M         Ans:       Fig. a.       Image: the vertical input frequency is 1500 Hz for fig. (a)       4M         Ans:       Fig. b.       Image: the vertical input frequency is 1500 Hz for fig. (b)       1M         Fig. b.       Y = 1.5 KHZ       Image: the vertical input frequency is 1500 Hz for fig. (b)       1M         Fig. b.       Explain	3. It can be obtained in wide ranges. 4. High sensitivity & accuracy	
Disadvantaces of PMMC meter: (Any two) 1. It is suitable for d.c. measurement only. 2. Comparatively high cost than moving iron type instrument. 3. Ageing of permanent magnet & spring introduce errors 4. Friction due to jewel- pivot suspension.2Mand fig. (b).Image: Calculate the vertical input frequency if horizontal frequency is 1500 Hz for fig. (a) and fig. (b).4Mand fig. (b).Image: Calculate the vertical input frequency if horizontal frequency is 1500 Hz for fig. (a) and fig. (b).4MAns:Fig. a. X=2, Y=2 Therefore, fy= X/Y x f Fy= 2.2 x 1500 Fy= 1.5 KHZIMFig. b. X=3, Y=2 Therefore, fy= X/Y x f x = 3/2 x1500Hz Fy= 2.25 KHZIMe)Explain the block diagram of function generator.4MAns:Block diagram:2MImage: Calculate the vertice of the spring of		
I. It is suitable for d.c. measurement only.       2. Comparatively high cost than moving iron type instrument.         3. Ageing of permanent magnet & spring introduce errors       4. Friction due to jewel- pivot suspension.         I)       Calculate the vertical input frequency if horizontal frequency is 1500 Hz for fig. (a) and fig. (b).       4M         IIII       IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII		
2. Comparatively high cost than moving iron type instrument.       3. Ageing of permanent magnet & spring introduce errors         4. Friction due to jewel- pivot suspension.       4. Friction due to jewel- pivot suspension.       4.         and fig. (b).       Image: Calculate the vertical input frequency if horizontal frequency is 1500 Hz for fig. (a) and fig. (b).       4M         Ans:       Fig a.       X=2, Y=2       IM         Therefore, fy= X/Y x f       Fy= 22 x 1500       Fy= 2.25 XHZ       IM         Fig b.       X=3, Y=2       IM       IM         Pielo diagram of function generator.       4M       M         e)       Explain the block diagram of function generator.       4M         Mas:       Elock diagram:       2M         (Working:       • The requency is controlled by varying the capacitor in LC or RC circuit. In this       2M		2M
3. Ageing of permanent magnet & spring introduce errors       4. Friction due to jewel- pivot suspension.         d)       Calculate the vertical input frequency if horizontal frequency is 1500 Hz for fig. (a) and fig. (b).       4M         and fig. (b). $input frequency if horizontal frequency is 1500 Hz for fig. (a) fig. (b).       4M         Ans:       Fig a.       input frequency if horizontal frequency is 1500 Hz for fig. (a) fig. (b).       4M         Ans:       Fig a.       input frequency if horizontal frequency is 1500 Hz for fig. (a) fig. (b).       1M         Ans:       Fig a.       input frequency is 1500 Hz for fig. (a) fig. (b).       1M         Ans:       Fig a.       input frequency is 1500 Hz for fig. (c) $		
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and fig. (b). i = 1 + 1 + 1 + 1 + 1 + 1 + 1 + 1 + 1 + 1		
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Fy= 2.25 KHZ       1M         e)       Explain the block diagram of function generator.       4M         Ans:       Block diagram:       2M         Image: Show of the second seco		IN
Explain the block diagram of function generator.       4M         Ans:       Block diagram:       2M         Image: Control of the product of the prod		43.5
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Ans:       Block diagram:       2M         Image: Ans:       Image: Block diagram:       Image: Block diagram:         Image: Ans: Block diagram: Image: Block diagram:       Image: Block diagram:       Image: Block diagram:         Image: Block diagram: Image: Block diagram:       Image: Block diagram:       Image: Block diagram:         Image: Block diagram: Image: Block diagram:       Image: Block diagram:       Image: Block diagram:         Image: Block diagram: Image: Block diagram:       Image: Block diagram:       Image: Block diagram:         Image: Block diagram: Image: Block diagram:       Image: Block diagram:       Image: Block diagram:         Image: Block diagram: Image: Block diagram:       Image: Block diagram:       Image: Block diagram:         Image: Block diagram: Image: Block diagram:       Image: Block diagram:       Image: Block diagram:         Image: Block diagram:	Fynlain the black diagram of function generator	
$\begin{split} \hline & freq. \\ \hline & freq. \\ \hline & freq. \\ \hline & control \\ \hline & freq. \\ \hline & control \\ \hline & co$		
$ \frac{Freq.}{Control} \underbrace{freq.}{Control} \underbrace{freq.}{Control} \underbrace{freq.}{Control} \underbrace{freq.}{Freq.} \underbrace{freq.}{Control} \underbrace{Freq.}{Co$	Mis. Diock diagram.	
$ \frac{Freq.}{Control} \underbrace{freq.}{Control} \underbrace{freq.}{Control} \underbrace{freq.}{Control} \underbrace{freq.}{Freq.} \underbrace{freq.}{Control} \underbrace{Freq.}{Co$		0
• The frequency is controlled by varying the capacitor in LC or RC circuit. In this	Freq. Control External Freq. Control VW External Freq. Control Control Freq. Control Circuit Freq. Circuit Circuit Freq. Circuit Freq. Circuit Freq. Circuit Circuit Circuit Freq. Circuit C	
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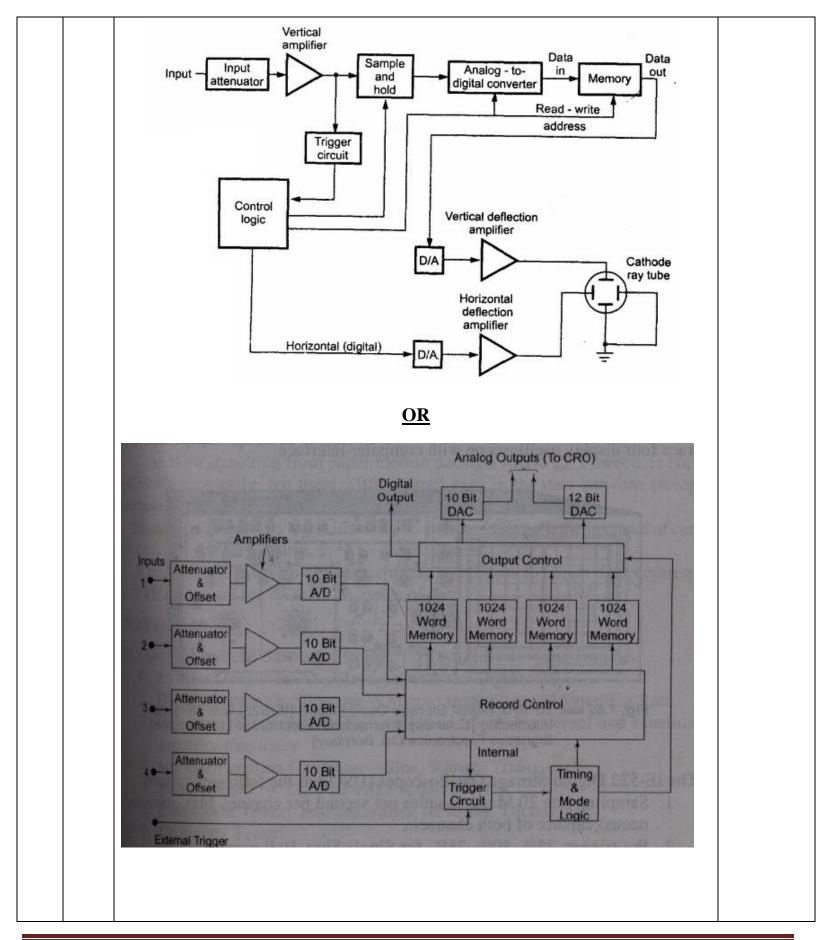


	<ul> <li>drives the integrator. The instrument produces sine, triangular and square waves with a frequency range of 0.01 Hz to 100 kHz.</li> <li>The frequency controlled voltage regulates two current sources.</li> <li>The upper current source supplies constant current to the integrator whose output voltage increases linearly with time, according to the equation of the output signal</li> </ul>	
	<ul> <li>voltage.</li> <li>t eout = -1 ∫ i dt C 0 An increase or decrease in the current increases or decreases the slope of the output voltage and hence controls the frequency.</li> </ul>	
	• The voltage comparator multivibrator changes states at a pre- determined maximum level of the integrator output voltage.	
	• This change cuts off the upper current supply and switches on the lower current supply.	
	• The lower current source supplies a reverse current to the integrator, so that its output decreases linearly with time.	
	• When the output reaches a pre-determined minimum level, the voltage comparator again changes state and switches on the upper current source.	
	• The output of the integrator is a triangular waveform whose frequency is determined by the magnitude of the current supplied by the constant current sources.	
	<ul> <li>The comparator output delivers a square wave voltage of the same frequency.</li> <li>The resistance diode network alters the slope of the triangular wave as its amplitude</li> </ul>	
	changes and produces a sine wave with less than 1% distortion.	
f) Ans:	Explain the working principle of wave analyser with neat block diagram. Block diagram:	4M 2M
	C	
	Signal input input input input input input input input input input input input input input input input R R Filter amplifier input input R Filter amplifier input inp	
	Signal input i	

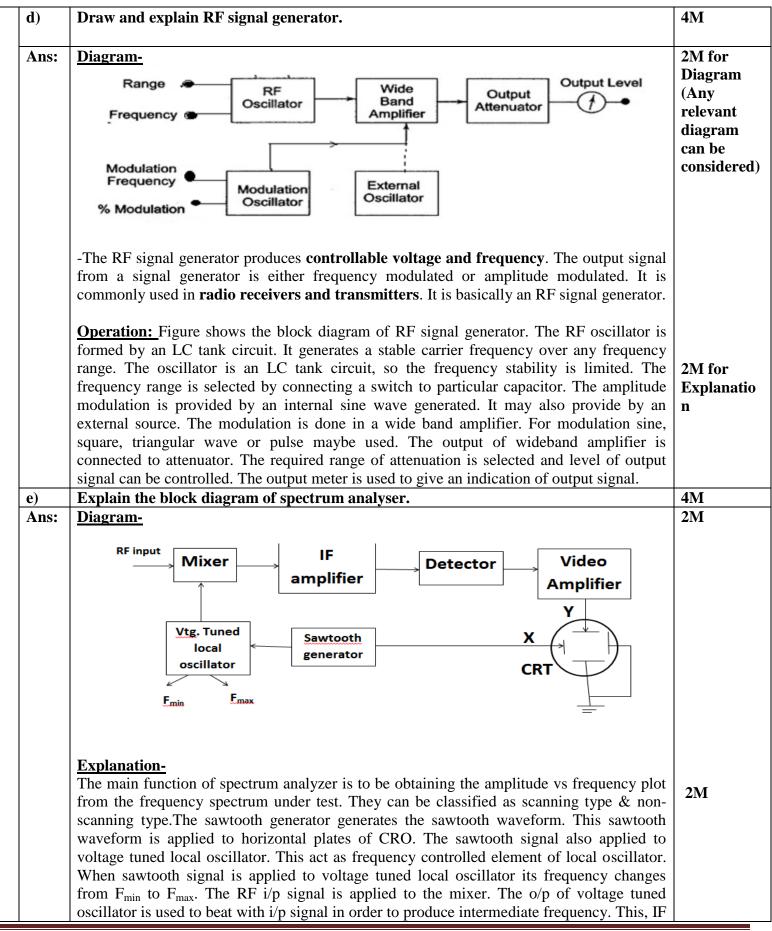


		• The intermediate stage is a full-wave rectifier to obtain the average value of input	
		signal.	
		• The indicating device is a simple DC voltmeter that is calibrated to read the peak	
		value of the sinusoidal input voltage.	
		• Since the LC circuit is tuned to a single frequency, it passes only the frequency to	
		which it is tuned and rejects all other frequencies.	
		• A number of tuned filters, connected to the indicating device through a selector	
0.5		switch would be required for a useful wave analyzer.	
Q.5		Attempt any four :	16-Total Marks
	a)	i) What is the resolution of 4 ½ DMM.	4M
	a)	i) Write two uses of Video pattern generator.	411/1
	Ans:	i) <u>Resolution of 4 <sup>1</sup>/<sub>2</sub> DMM</u> : The number of digit positions used in a digital meter	2M
	<b>AII5</b> .	determines the resolution. Hence a four and a half digit meter could display up to 19999.	2111
		Resolution can also be defined as the ratio of change in analog output voltage resulting	
		from a change of 1 LSB at the digital input.	
		ii) <u>Uses of Video pattern generator</u> : It is a device which can generate video signals that	
		can be fed to a TV or video monitor. The pattern consists of geometrical figures such as	
		circles, ellipses, horizontal/vertical lines and bars, checker board, dots etc.	
		The various patterns are used for	
		(1)The <b>horizontal pattern</b> is used to check vertical linearity.	2M
		(2) The <u>vertical pattern</u> is used to check horizontal linearity	
		(3) The <u>cross hatch pattern</u> is used to check vertical and horizontal linearity	
		simultaneously and more precisely.	
	1)	(4) <b>FM signal</b> is used for aligning sound IF as well as discriminator circuit.	43.4
	b)	Find the phase relation for following fig. (c) and fig. (d).	<b>4M</b>
		5 81	
		-Ar/ r	
		Fig. (c) Fig. (d)	
	Ans:	Θ=Sin <sup>-1</sup> A/B	
	AU2.	where $\mathbf{A} = \mathbf{Y}$ axis intersect $\mathbf{B} =$ maximum vertical deflection	
		1) A=5, B=7 $\Theta$ =Sin <sup>-1</sup> A/B = 45.58 <sup>0</sup>	2 M
		2) A=0, B=7 $\Theta = \sin^{-1}A/B = 0^{0}$	2 M 2 M
	<b>c</b> )	Draw the block diagram of DSO.	4M
	Ans:	Block diagram-	4M for
			Labeled
			diagram











		component is produced when corresponding component is present in i/p signal. The resulting, IF signal is applied to detector & video amplifier. The IF component is amplified & detected & then it is applied to vertical deflecting plates of CRO, producing a plot of amplitude vs frequency.	
	<b>f</b> )	What is the use of Q meter? Draw its neat diagram.	4M
	Ans:	Q-meter :	2M for Q-
		<ul> <li>The Q meter is an instrument which is designed to measure the value of Q directly and is useful for measuring the characteristics of coils and capacitors i.e. it used for testing of inductors and capacitors.</li> <li>The Q factor is equal to Q = ωL / R where ω = Angular frequency at resonance, L = inductance, R = Effective resistance of coil.</li> </ul>	meter uses
		Oscillator $R_{sh} \neq E$ $C_d$ Tuning $C$ $E_C$ $O$ - Electronic voltmeter voltmeter	2M for diagram (Any relevant answer can be considered)
		Fig. Q meter	
Q.6		Attempt any four :	16-Total Marks
	<b>a</b> )	Draw dual trace CRO and explain the function of AltiChop mode.	<b>4</b> M
		Channel A Attenuator and preamplifier Channel B Attenuator and preamplifier Channel B Attenuator and preamplifier B Attenuator B Attenuator B Attenuator B Attenuator Delay line A S10 X-Y mode B Sweep generator or time base S3 Channel B Attenuator Delay line B Sweep generator or time base S3 Channel B Attenuator B Attenuator S2 Channel B Attenuator S2 Channel B Attenuator S2 Channel B Attenuator Channel B Attenuator Channel B Attenuator Channel B Attenuator Channel B Attenuator Channel Ch	
		Line Trigger selector switch	
		<ul> <li>In "alternate mode" electronic switch connects the two channels A &amp; B alternately in successive cycles of sweep generator. The alternate mode cannot be used for displaying very low frequency signal.</li> <li>In "Chop mode" electronic switch will make several transition from one channel to the other channel during one sweep.</li> </ul>	1M 1M

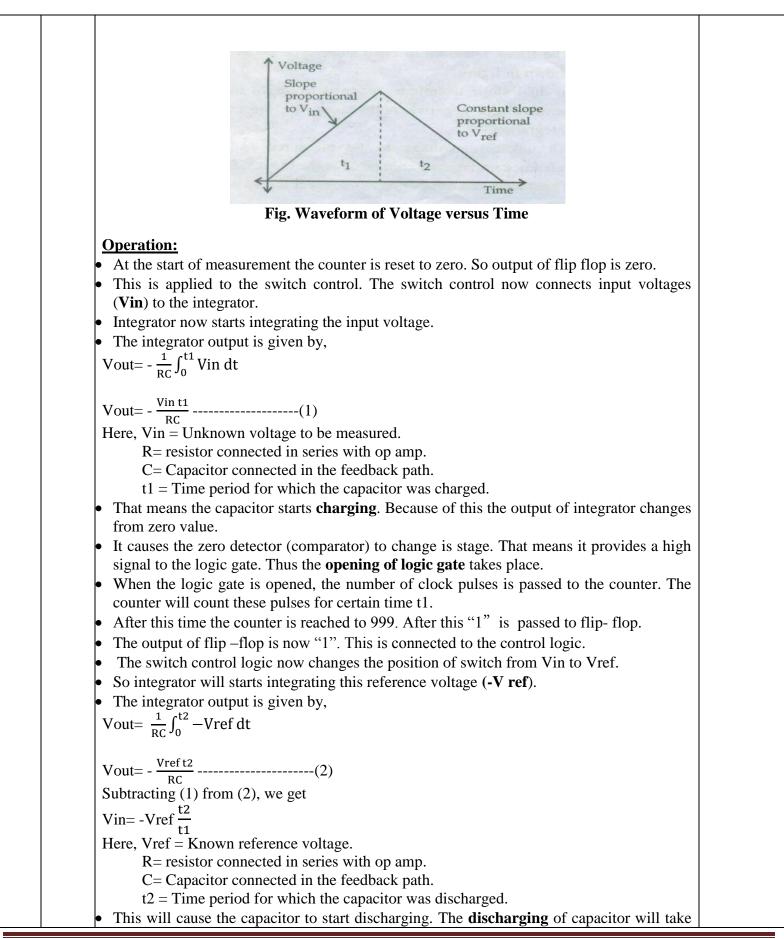


	Τ	
Ans:	1) <u>Using DMM:</u>	2M
	i) <b><u>DMM for diode testing</u></b> : Digital multimeters can test diodes using one of two methods:	
	Diode test mode and resistance mode.	
	<b>Diode Test mode</b> : A diode is best tested by measuring the voltage drop across the diode	
	when it is forward-biased. A forward-biased diode acts as a closed switch, permitting	
	current to flow. A multimeter Diode Test mode produces a small voltage between test	
	leads. The multimeter then displays the voltage drop when the test leads are connected	
	across a diode when forward-biased.	
	ii) <u>DMM for transistor testing:</u>	
	Assuming you know if the transistor is NPN or PNP, and assuming you know where B, C,	
	and E are, then just test the B-C junction and the B-E junction as if they were standard	
	diodes. if one of those junctions is a "bad diode", then the transistor is bad. Also, check the	
	resistance from C to E using a higher Ohms scale (say, the 2 Meg scale). Be sure your	
	fingers don't touch the metal test points or you will just measure your skin resistance. If the	
	transistor is good, you should get an open-circuit reading from collector to emitter.	
	2)Using CRO: Component testing mode i.e. CT Mode is used to test various	
	components.	
	i) <u>CRO for Diode testing</u> : when diode is forward biased, a current will flow, producing	2M
	voltage drop across 1k ohm resistor. This is applied to vertical input. If diode is good, the	
	current must be unidirectional & must show a curve which rises vertically from its	
	horizontal position. This is shown in fig 1. The horizontal portion represents very small i.e.	
	almost zero current in reverse direction. The angle between rising portion & horizontal	
	portions indicates condition of the diode as shown in fig 2. If current rise is not shown at	
	all, then we get only horizontal trace on CRO & diode can be concluded to be open i.e.	
	faulty. This is shown in fig 3.	
	Fig 1. Good Diode Fig 2. Parrially or shorted diode Fig 3. Open diode i.e. Faulty	
	ii) <u>CRO for transistor testing</u> : The transistor consists of two p-n junctions. Each p-n	
	junction can be tested using the procedure describe for diode testing, by this way transistor	
	can also be tested by CRO.	
	i) Draw characteristics of pulse and label it.	4M
	ii) Define - Rise Time, Overshoot.	
5:	Diagram-	2M for
		correct
		labeled
		diagram



	Amplitude       Setting time       90%         10%       Pulse width       50%         10%       Rise time       Fall         10%       Period T         Fig. characteristics of pulse	
	<b><u>Rise time:</u></b> The time required for the pulse to reach from 10% to 90% of it's amplitude, is called Rise time. <b><u>Overshoot</u></b> : It is maximum height immediately following leading edge.	1M 1M
<b>d</b> )	Explain the block diagram of Dual slope DVM.	4M
Ans:	<ul> <li>Dual Slope Integration Type DVM:</li> <li>The ramp type DVM (single slope) is very simple yet has several drawbacks. The major limitation is the sensitivity of the output to system components and clock.</li> <li>The dual slope techniques eliminate the sensitivities and hence the mostly implemented approach in DVMs.</li> <li>Dual slope integration technique is basically voltage to time conversion method. In thiscase, integration is done for unknown voltage and then the same integrator is used to dothe integration with reverse slope. So, this is called as dual slope integration method.</li> <li>Image: Some the sensitivity of the output to system components and clock.</li> <li>The dual slope integration technique is basically voltage to time conversion method. In thiscase, integration is done for unknown voltage and then the same integrator is used to dothe integration with reverse slope. So, this is called as dual slope integration method.</li> <li>Image: Comparison of the sensitivity of the output to system component of the same integrator is used to dothe integration with reverse slope. So, this is called as dual slope integration method.</li> <li>Image: Comparison of the sensitivity of the output to system component of the sensitivity of the output to system component of the sensitivity of the output to system conversion method.</li> <li>Image: Comparison of the sensitivity of the output to system component of the sensitivity of the output to system component of the sensitivity of the output to system conversion method.</li> <li>Image: Comparison of the sensitivity of the output to system comparison of the sensitivity of the output to system comparison of the sensitivity of the output to system comparison of the sensitivity of the output to system comparison of the sensitivity of the output to system comparison of the sensitivity of the sensitivity of the output to system comparison of the sensitivity of the sensitivity of the sensitivity of the sensitity of the sensitity of the sensitivity of the sen</li></ul>	2M for diagram 2M for explanation







	place for the time period. The discharging path is having a constant negative slope. This	
	slope is as shown in Fig.	
	• A stage will be reached at which output of integrator becomes zero.	
	• This stage is obtained at the end of time period t2. At this instant the output of zero	
	detectors gets changed. This will cause the closing of logic gate.	
	• Now the pulses from clock are not allowed to pass towards the counter. The counting	
	operation is completed.	
	Then the data from counter is passed to the digital readout for display purpose.	
<b>e</b> )	List the specification of DMM.	<b>4</b> M
Ans:	Specifications of DMM are as follows:	1M each
	1. D.C. Voltage:	for any
	• Voltage range from +20V to +1000V	correct 4
	• Accuracy about +0.03%	points
	• Resolution is about 10µV	
	2. AC Voltage:	
	• Voltage range from 200mV to 750V	
	Accuracy is frequency dependent	
	• Resolution: $10\mu V$	
	3. Resistance:	
	• Resistance range from $200\Omega$ to $20 \text{ M} \Omega$	
	• Accuracy: +0.1% of reading	
	4. DC current:	
	• Current range from $+200\mu A$ to 2A	
	• Accuracy +0.3% of reading	
	<ul> <li>Resolution +0.01µA</li> </ul>	
	5. A.C Current:	
	• Range from 200µA to 2A	
	<ul> <li>Accuracy depends on frequency</li> </ul>	
	recuracy depends on nequency	
<b>f</b> )	Give the functions any four knob of following:	<b>4</b> M
,	i) X-shift on CRO.	
	ii) CT MODE Button on CRO.	
	iii) Symmetry knob on function generator.	
	iv) Level knob on function generator.	
	v) V/div on CRO.	
	vi) Mono/Dual Button on CRO.	
Ans:	i) X-shift on CRO: Controls the horizontal position of the display i.e moves the spot across	1M each
	the screen left and right.	(any
	ii) CT MODE Button on CRO: To test different components	relevant
	iii) Symmetry knob on function generator: Select either positive pulse/ramp or negative	answer can
	pulse/ramp	be
		• 1 1)
	iv) Level knob on function generator: Determines where on the edge the trigger point occurs	considered)
	i.e. it's a Variable control, selects the trigger point on the displayed waveform.	considered)
	<ul> <li>i.e. it's a Variable control, selects the trigger point on the displayed waveform.</li> <li>v) V/div on CRO: To control the gain/attenuation of vertical amplifier</li> </ul>	considered)
	i.e. it's a Variable control, selects the trigger point on the displayed waveform.	considered)