

Total No. of Questions : 10]

SEAT No. :

P2225

[Total No. of Pages : 3

[5254]-558

B.E. (Mechanical Sandwich Engineering)
CAD/CAM AND AUTOMATION (Elective -I)
(2012 Pattern)

Time : 2½ Hours]

[Max. Marks : 70

Instructions to the candidates:

- 1) *Answer five questions.*
- 2) *Neat diagrams must be drawn wherever necessary.*
- 3) *Figures to the right indicate full marks.*
- 4) *Use of logarithmic tables slide rule, Mollier charts, electronic pocket calculator and steam tables is allowed.*
- 5) *Assume suitable data, if necessary.*

- Q1)** a) Explain reflection of geometrical entity about line $y = mx + c$, with schematic representation and write concatenated transformation matrix. [6]
- b) Compare analytical and parametric curve with example of circle. [4]

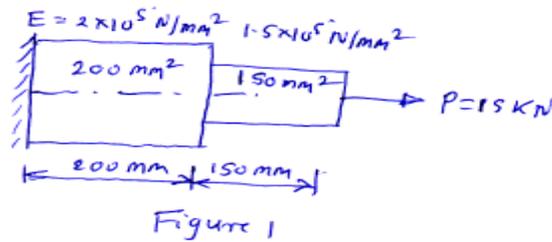
OR

- Q2)** a) Compare geometrical Transformation and mapping. [4]
- b) Circle is drawn with centre at(5,5) and radius 4 units write parametric equation of circle in recursive form and find number of points on circle if increment in angle $\Delta\mu = 30^\circ$. [6]
- Q3)** a) Compare Brep and CSG Technique of solid modeling with neat sketch. [6]
- b) Derive expression of stiffness matrix for truss elements. [4]

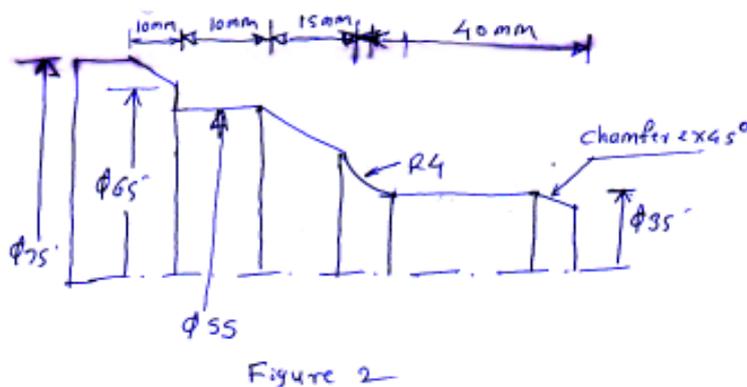
P.T.O

OR

Q4) An axial step bar is shown in figure 1. Determine deflection, stresses and reaction force. [10]



- Q5)** a) Explain linear, circular CW and circular CCW interpolation with G word format. [6]
- b) Write CNC part program for roughing and finishing cycle using canned cycle for turned components as shown in figure 2. Assume suitable cutting data: [12]



OR

- Q6)** a) Explain G28 G04 M03 G41 code in part programming. [6]
- b) Explain canned cycle for drilling and boring for milling components. [6]
- c) Compare the incremental and absolute method of programming with G code. [6]

- Q7)** a) Classify various R.P. process. [6]
b) Explain 3-D printing process. [10]

OR

- Q8)** a) Explain Laminated object manufacturing (LOM) modeling method of rapid prototyping with advantages and limitation. [12]
b) List R.P. applications. [4]
- Q9)** a) Draw work envelopes for various robot configurations. Explain the articulated configuration Robot with neat sketch. [10]
b) Explain mechanical gripper with figure. [6]

OR

- Q10)** a) Compare various Automations. [8]
b) Explain various elements of FEM. [8]

